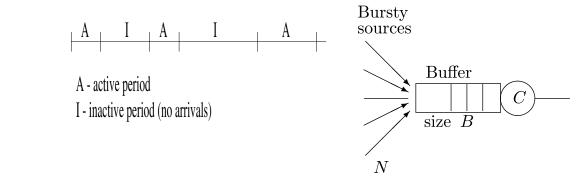


Parallel Simulation of ATM Switches A.S.M^CGOUGH, I.MITRANI

1: What is an ATM switch ?

An ATM switch is a "statistical multiplexor" switch which forms part of an ATM network.

- Packets of data, called "cells", arrive from several input streams.
- Cells are combined in the order of arrival.
- Cells are output onto a single departure stream.



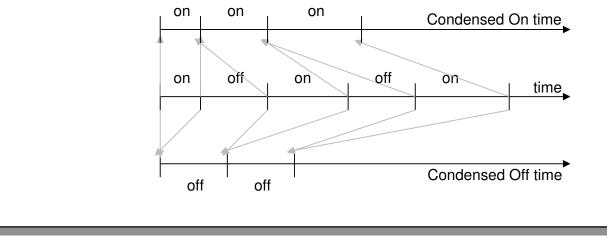
Assumptions for the simulation.

- Cells are of fixed length and arrive from N input streams.
- The sources have a Bursty nature, with periods of activity and inactivity.
- The switch can handle C cells per unit of time.
- There is a fixed amount of buffer space in the switch for B cells.
- When the buffer is full any cell that arrives will be lost.

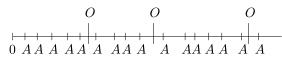
2: Outline of method

The program iterates the following stages until M cells have been simulated.

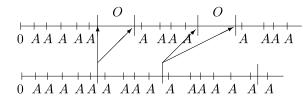
- Generate arrivals
 - Arrival assumptions
 - Any distribution can be simulated.
 - But with bursty "on" / "off" property.
 - Generate B arrivals for each input stream, taking into account the active and inactive periods. (on and off periods)
 - Generate on / off periods in advance.
 - On periods are condensed time line with off periods removed.
 - Off periods are condensed time line with on periods removed.



• Generate arrival instances on the condensed "on" time line using parallel prefix algorithm.



• Expand the on time line to become the whole time line.



- Merge arrivals
 - Want to merge the first B cells, w.r.t. time, from the N input sources.
 - Use a balanced merge method where each process handles E cells.
 - Process i will merge from cell iE to (i+1)E -1.
 - Therefore if E = B/P, then the first B cells will be merged over the P processes.
 - All remaining cells are left for the next iteration of the program.

Calculate cell losses

- Mark cells that are clearly accepted or lost.
- Mark all other cells as unsure & calculate the number of cells that need to be lost in order for their acceptance.
- Iterate over unsure cells to determine their acceptance.
- Calculate departures
 - Use parallel prefix method to compute departure times of accepted cells.
- Replace lost cells
 - Use a serial version of the algorithm to top the iteration back up to B cells if any cells have been lost in this iteration.

3: Parallel Prefix Algorithm

• Given n objects

 $a_1, a_2, \dots a_n$

• And an associative operation \oplus .

• Need to compute the prefix sums

 $a_1 \ , \ a_1 \oplus a_2 \ , \ a_1 \oplus a_2 \oplus a_3 \ , \ a_1 \oplus a_2 \oplus a_3 \oplus a_4 \ , \ \dots \ , \ a_1 \oplus a_2 \oplus \dots \oplus a_n$

• This can be efficiently solved using the parallel prefix algorithm.

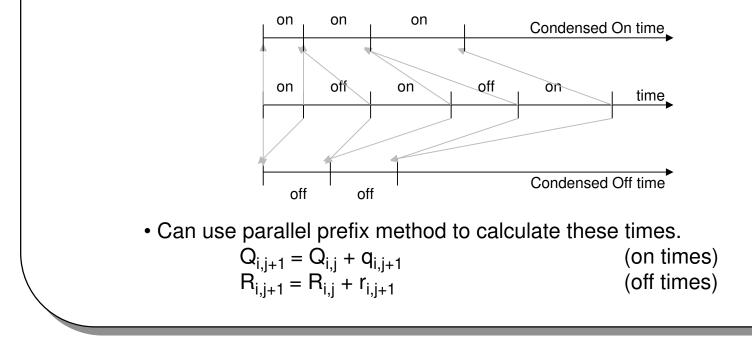
- Time requirement approximately of the order O(n/P).
- Thus almost linear speed-up.

• Eg for computing the arrivals.

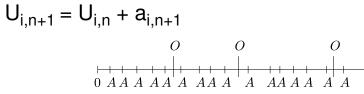
- $U_{n+1} = U_n + a_{n+1}$.
- This is a prefix sum with associative operation of normal addition.

4: Generate arrivals

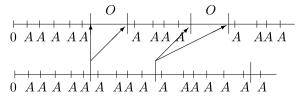
- Arrival assumptions
 - Any distribution can be simulated.
 - But with bursty "on" / "off" property.
- Generate on / off periods in advance.
 - On periods are condensed time line with off periods removed.
 - Off periods are condensed time line with on periods removed.



- Generate the next B arrivals.
 - Generate arrival instances on the condensed on time line using parallel prefix algorithm.



• Expand the on time line to become the whole time line.



Achieved by solving the relation

$$\sum_{j=1}^{k-1} q_{i,j} < U_{i,n} \le \sum_{j=1}^{k} q_{i,j} ,$$

for each cell in the block.

• And then adding k-1 off periods to the condensed on time.

$$A_{i,n} = U_{i,n} + \sum_{j=1}^{k-1} r_{i,j}$$

• This expansion can be done in parallel as each cell is independent.

- Calculating number of on / off periods to compute.
 - Can be predicted from theory. [see paper]
 - Values doubled for use in program.
 - Results within 5% of theoretical values.

5: Merge arrivals

- Want to merge the first B cells, w.r.t. time, from the N input sources.
 - Use a balanced merge method where each process handles E cells.
 - Process i will merge from cell iE to (i+1)E -1.
 - Therefore if E = B/P, then the first B cells will be merged over the P processes.
- Balanced partitions are achieved by iterating the following steps for each boundary.
 - Take an estimate e for the value that will give iE cells before it.
 - Use a binary search algorithm to compute the number of cells in each stream less than e and sum to give total number less than e.
 - Use this total to reassess the estimate for the partitioning value.
 - too many ⇒ reduce estimate.
 - too few → increase estimate.
 - With good choice of estimates it is possible to half the search space for the correct value of e at each iteration.

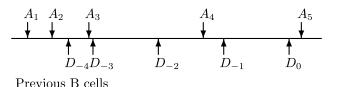
- Once boundary's are found.
 - Each process can merge its cells independently of the others.
 - Thus the merges can be performed in parallel.
 - Each process uses a standard serial merging algorithm.

6: Calculating loss and accepts

- A record of the departure times for the previous B cells needs to be kept for this stage labelling them from 1-B, 2-B, to 0.
- The current B cells will be labelled as 1, 2, to B.
- Ascertain the states of each cell:
- Cell i is accepted if
 - The cell i-B (from departure list) has departed when cell i arrives.
- Cell i is lost if
 - The cell i-B has not departed when cell i arrives and
 - All cells, before i-B, from the departure block have departure times after cell i arrives.
- Cell i is unsure if
 - The cell i-B has not departed when cell i arrives and
 - There is a cell i-B-j in the departure list that departs before cell i arrives.
 - Thus if at least j cells are lost from the current arrival block before cell i then cell i can be accepted.

Eg. for case of buffer size 5.

Current B cells





- Cells 1 and 2 will be lost.
- Cell 3 is unsure, but will be accepted if 2 cells are lost before it.
- Cell 4 is unsure, but will be accepted if 1 cell is lost before it.
- Cell 5 is accepted.
- Each process is thus allocated B/P cells to ascertain their state as above.
 - These can be performed independently.
 - And thus in parallel.

- Cell acceptance for the remaining unsure cells. Iterate the following stages:
 - Each process calculates the number of cells lost in it's block.
 - Each process calculates the maximum number of cells that can be lost in it's block (assumes all unsure cells are lost).
 - Each process can now compute a maximum and minimum for the number of cells lost in the buffer before it's own block.
 - If for an unsure cell, j < minimum, then the cell can now be accepted. and marked as such.
 - If for an unsure cell, j > maximum, then the cell is now lost and marked as such.
 - This will be repeated until all processes have maximum = minimum.
 - Will take no more than P iterations.
 - If cell loss is low will only take a few iterations.
 - Each process can work in parallel.

7: Departure times

- Computation of departure times for remaining cells is performed using the parallel prefix method using the matrix product in the (max, +) algebra given by Greenberg et all (1991) as the associative operation.
- Serial version of the above algorithm used to top the buffer back up to B cells.
- Assumed cell loss is low enough that parallelising the top up would be more time consuming.

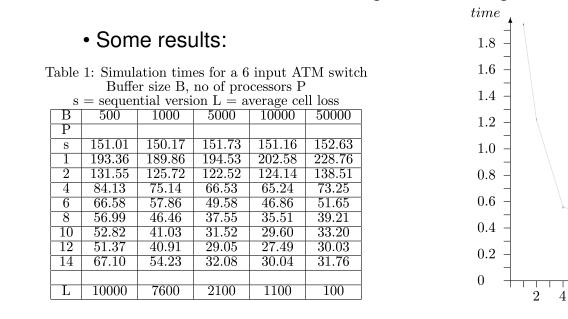
8: Conclusion and results

• Speed-up obtained from the algorithm is almost linear O(M/P).

• Even in cases where the losses are 1% of sent cells.

• Can be used to model many arrival stream properties.

• Confidence intervals for timings below are good - within 1 second.



6 8

10

12 14

processors