

# analysis and algorithms for restart

Aad van Moorsel

University of Newcastle

Katinka Wolter, and Philipp Reinecke

Humboldt University, Berlin

# example application

**when should you click reload?**



# credit

much work has been done in

- checkpointing
- rejuvenation
  - restart is much simpler
  - appropriate
- gives us some insights

# contents

- mathematical formulation
- restart to improve first moment of completion time
- restart to improve higher moments
- geometric approximation
- optimising different moments simultaneously
- 'engineering' rule for size of restart interval

# problem definition

- any task
- when it doesn't succeed quick enough, it is retried

model assumptions:

- we know the distribution (e.g. of download time)
- retries are independent, identically distributed (iid)

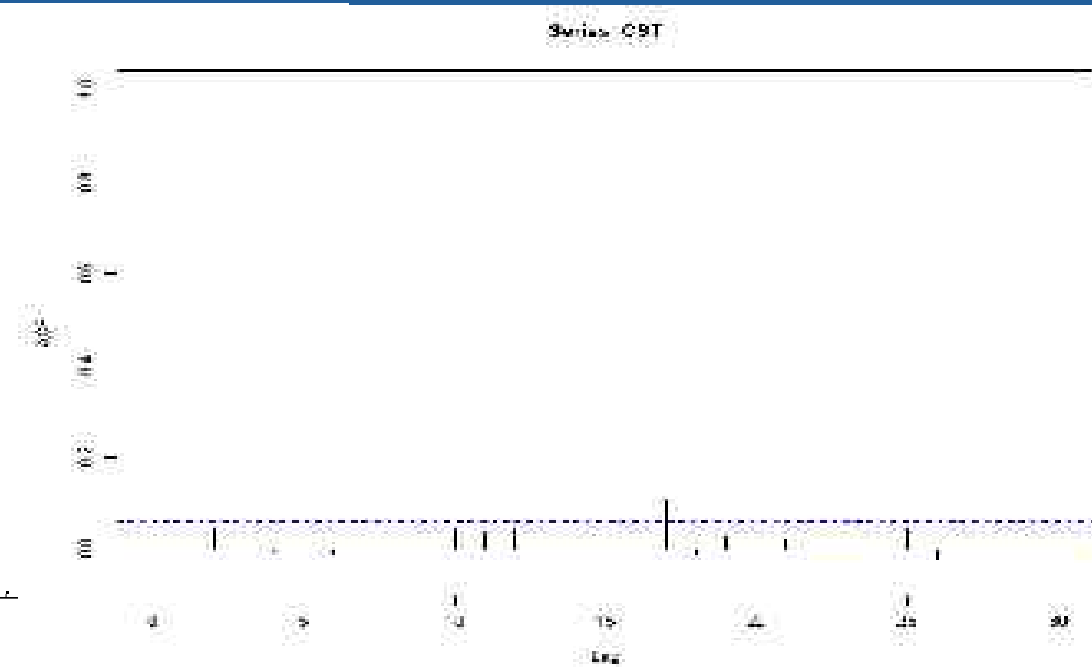
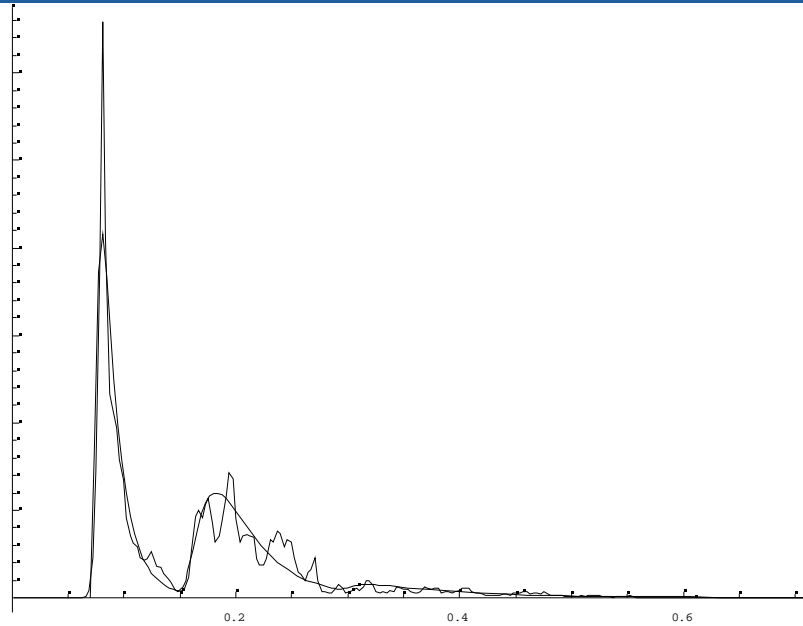
turns out to be realistic for Internet applications (SAForum 2004)

formal:

$$E[T] < E[T - \tau | T > \tau]$$

- always true for hyper-exponential distribution
- never true for hypo-exponential distribution (Erlang)
- does not hurt nor help for exponential distribution (=)

# independence



data overlaid with 3 lognormal distributions

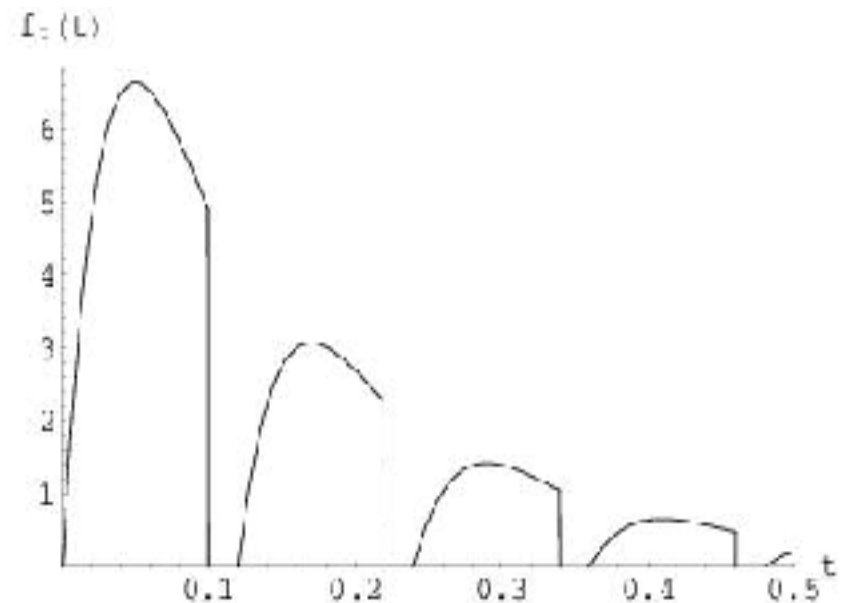
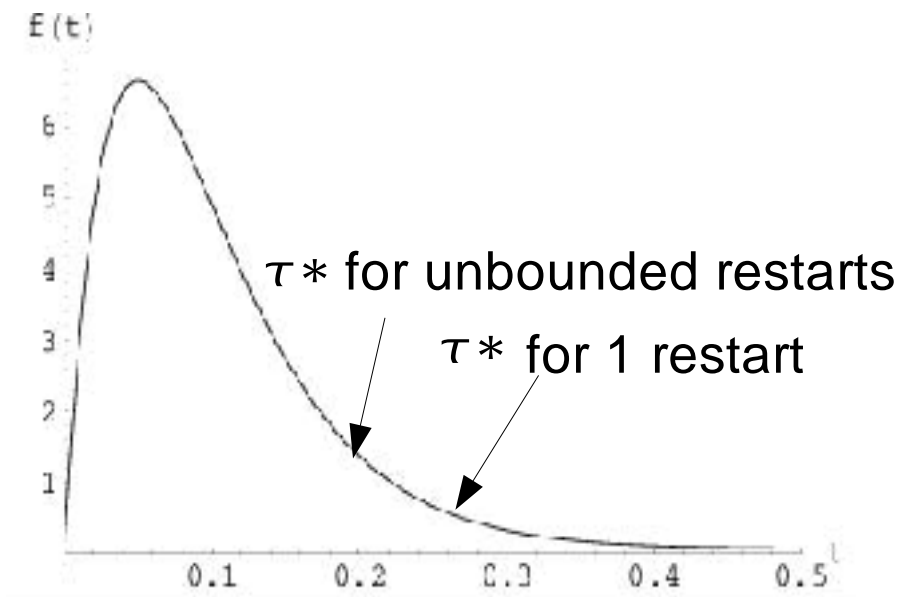
correlation for same URL

# completion time distribution

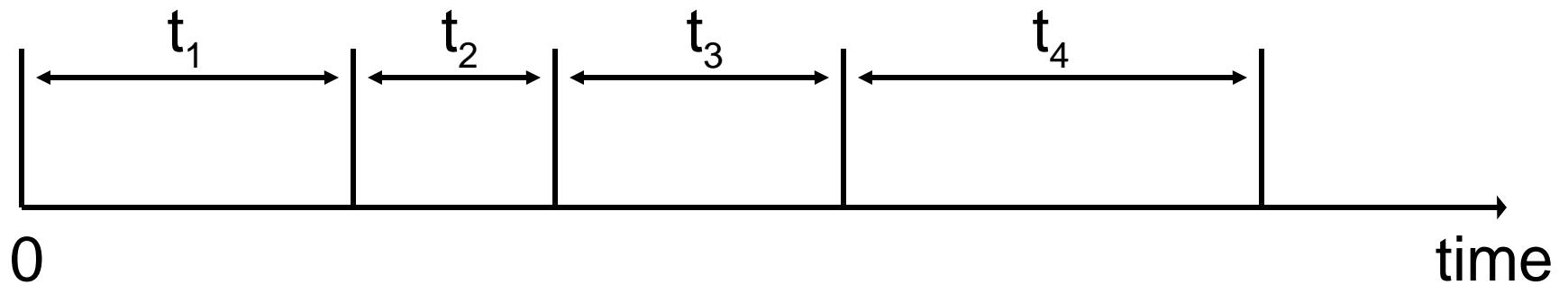
$T \sim$  hyper/hypo-exponential

$$T = 0.9 T_1 + 0.1 T_2$$

$T_1 = \text{Erlang}(2) \text{ lambda} = 20, T_2 = \text{Erlang}(2) \text{ lambda} = 2$



# problem formulation

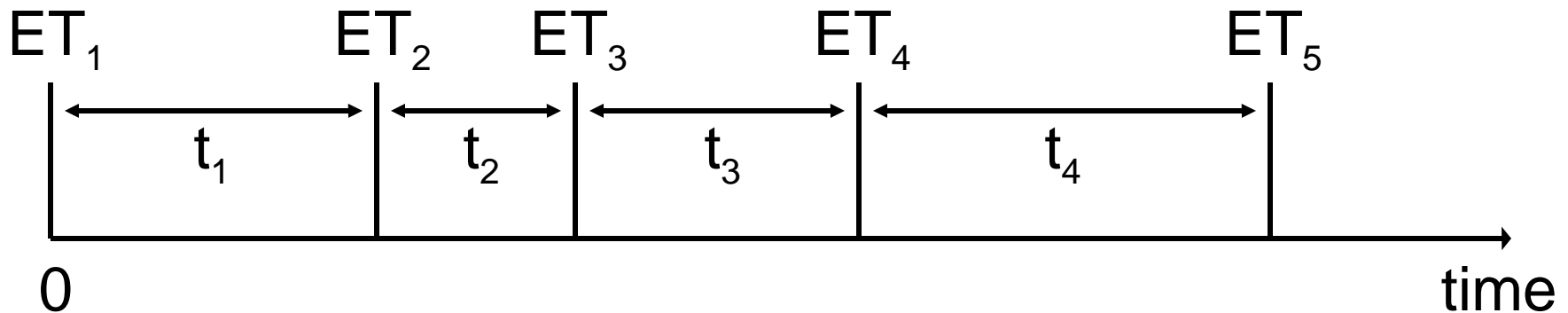


which values  $t_1, t_2, t_3, \dots$  minimise completion time?

	first moment	higher moments
finite # restarts	?	?
infinite # restarts	?	?

# first moment

# first moment, finite # restarts



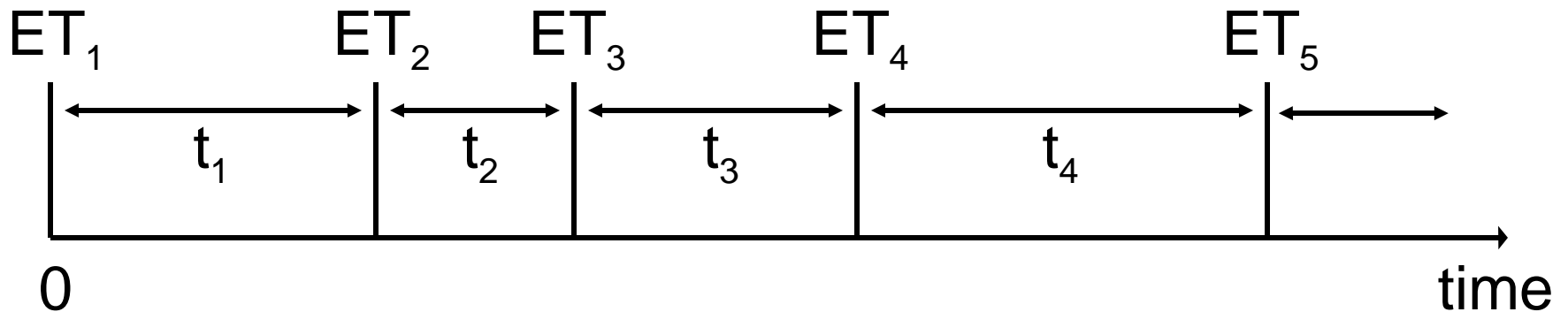
$$ET_K = ET$$

$$ET_{K-1} = F(t_{K-1}) \cdot M(t_{K-1}) + (1 - F(t_{K-1})) \cdot (t_{K-1} + ET_K)$$

backward algorithm:

for  $k = K, K-1, \dots, 1$  find  $t_k$  that minimises  $ET_k$ ;

# first moment, infinite # restarts



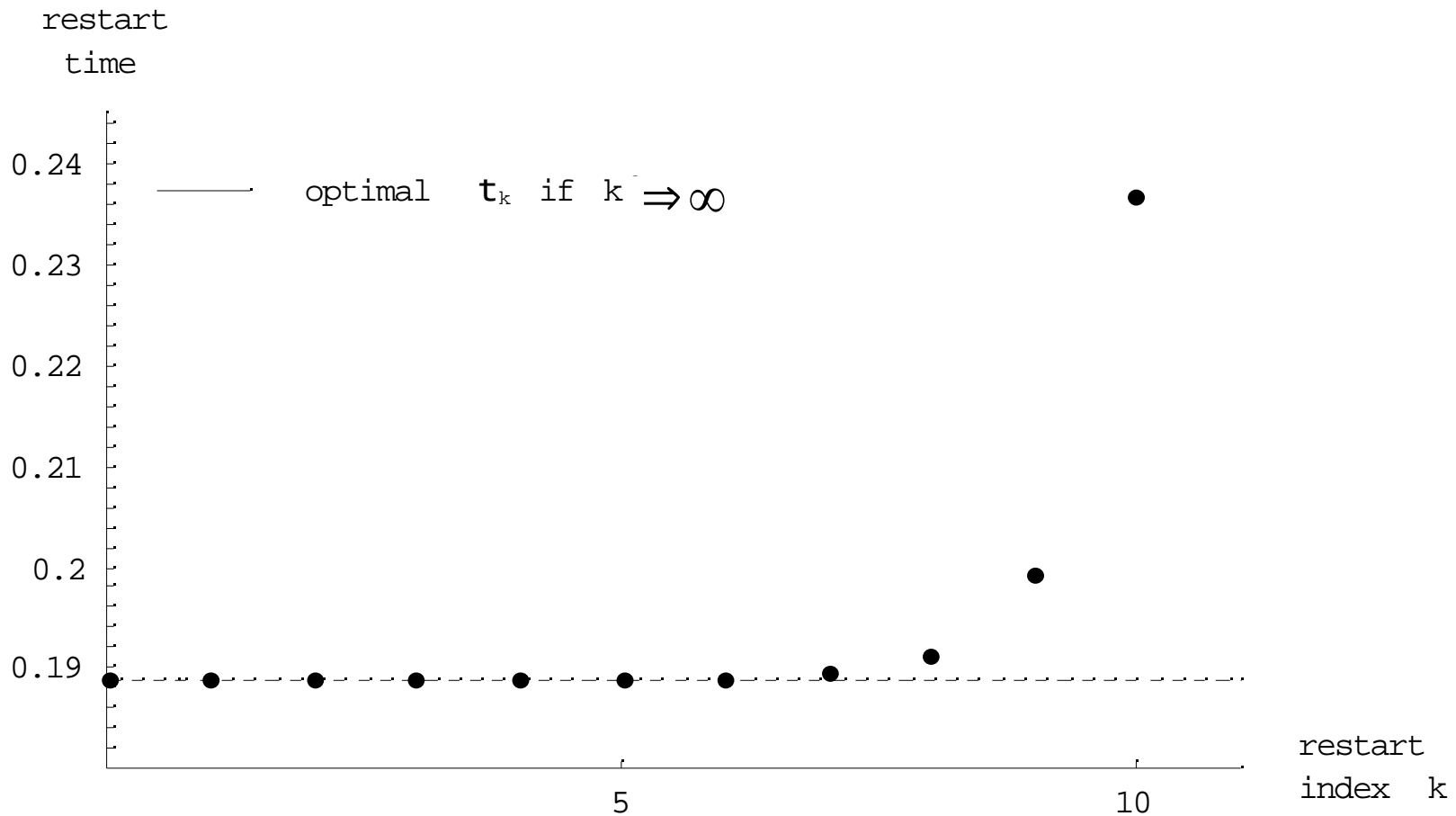
$$ET_1 = ET_2 = \dots = ET_{K-1} = ET_K = \dots = ET_\infty$$

*constant* optimal restart time  $t_1 = t_2 = t_3 = \dots = t_\infty$

find  $t_\infty$  that minimises

$$ET_\infty = M(t_\infty) + (1 - F(t_\infty)) \cdot t_\infty / F(t_\infty)$$

# first moment: optimal restart times

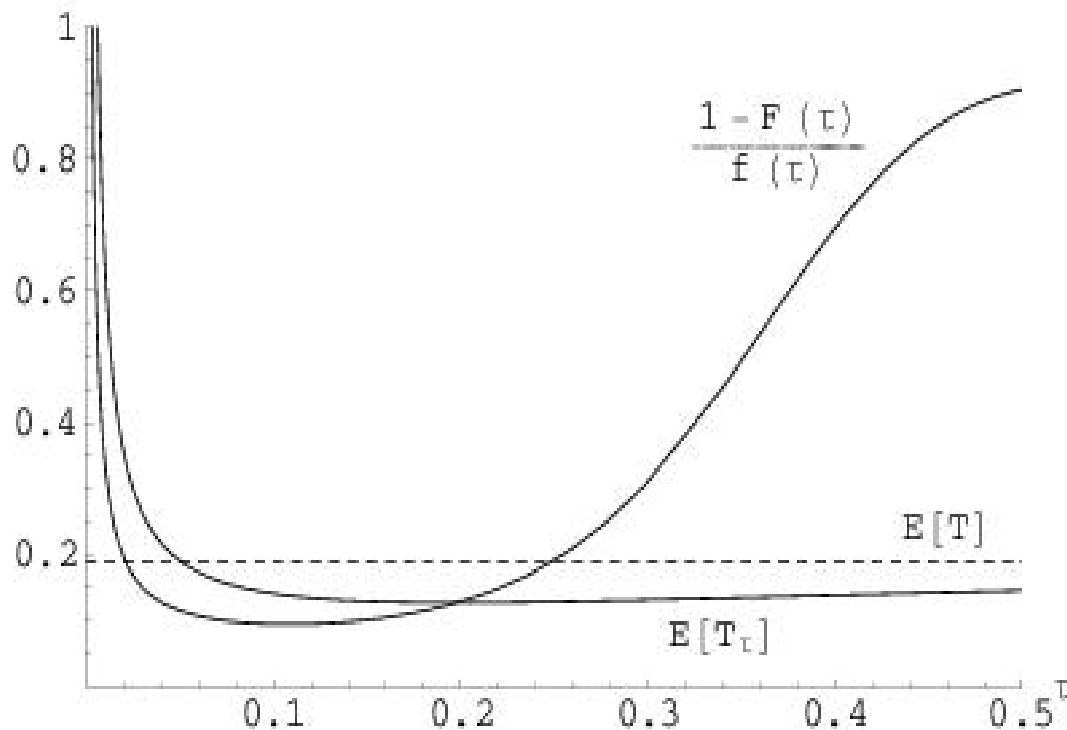


Lognormal distribution,  $\mu = -2.31$ ,  $\sigma = 0.97$

# optimal restart time for unbounded restarts

inverse hazard rate

$$\frac{1 - F(\tau^*)}{f(\tau^*)} = \mathbf{E}[\tau^*] + c$$



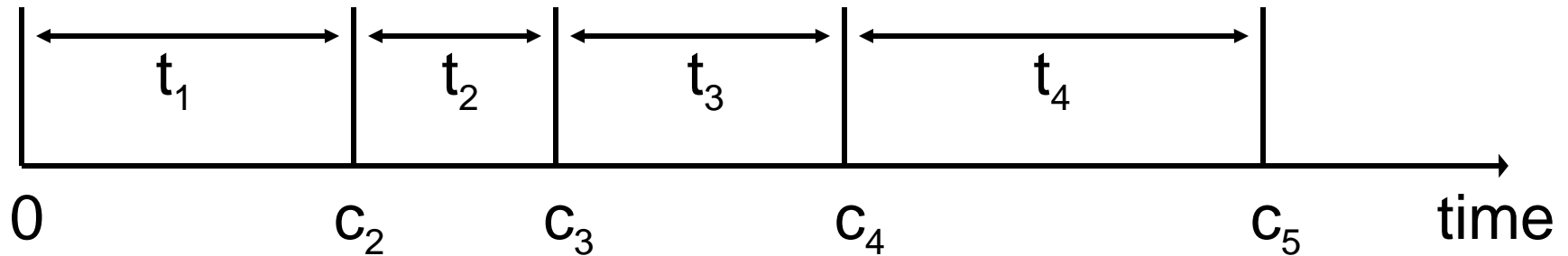
$c = 0$

# results for first moment

	first moment	higher moments
finite # restarts	backward algorithm K optimisations	?
infinite # restarts	constant 1 optimisation	?

# higher moments

# sensitivity to shift



$$E(c + T) = c + ET$$

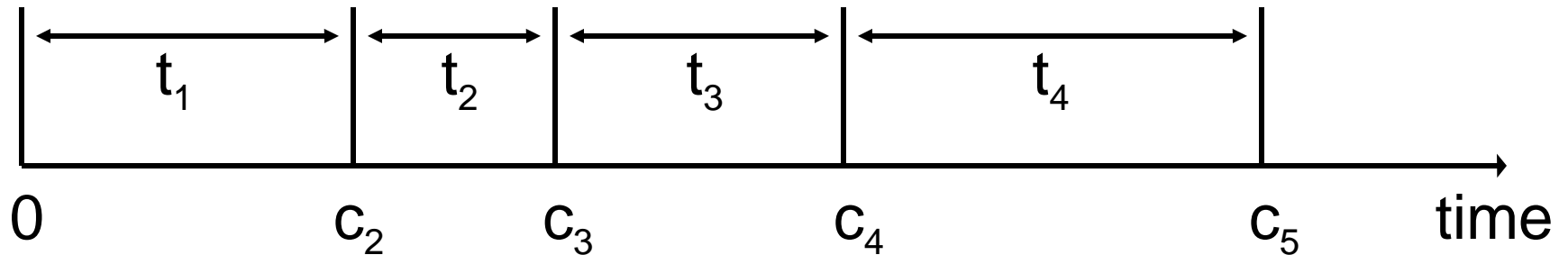
i.e., minimising  $E(c + T) =$  minimising  $ET$

but:

$$E(c + T)^2 = c^2 + 2.c.ET + ET^2$$

i.e., minimising  $E(c + T)^2 \neq$  minimising  $ET^2$

# sensitivity to shift



first moment, optimal  $t_k$  independent of earlier restarts

- finite: backward algorithm works
- infinite: constant

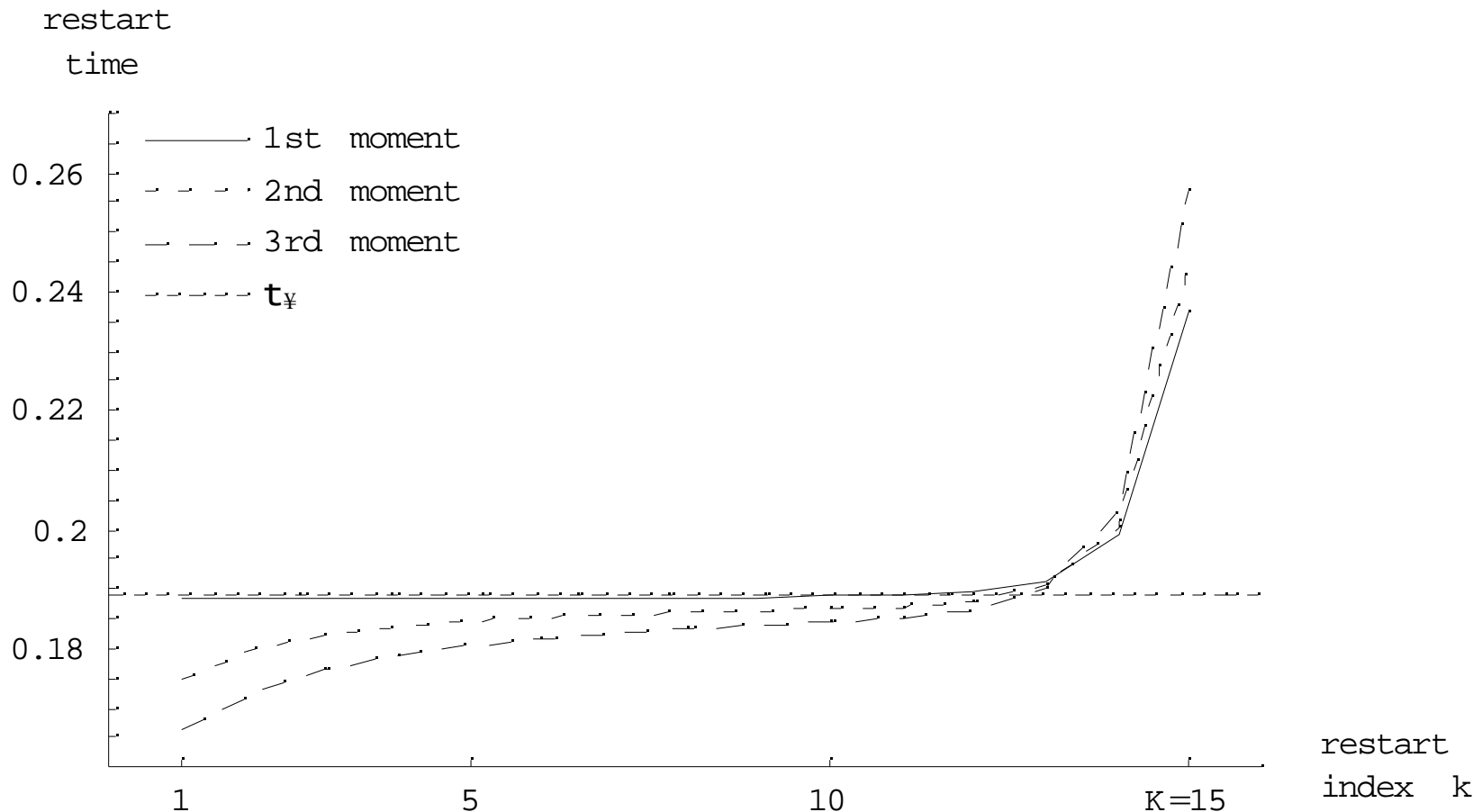
higher moments:

- finite: backward algorithm fails
- infinite: not constant (btw, papers have claimed the opposite)

luckily, optimal restart times for higher moments only depend on the *sum* of preceding restarts

resolution: backward/forward algorithm

# first three moments: optimal restart times



Lognormal distribution,  $\mu = -2.31$ ,  $\sigma = 0.97$

# results for all moments

	first moment	higher moments
finite # restarts	backward algorithm  K optimisations	backward/forward iteration  N.K optimisations
infinite # restarts	constant  1 optimisation	first moment approximation & backward/forward at start and end  $N_1.K_1 + N_2.K_1$

results for higher moments in UKPEW 2004

# properties and related issues

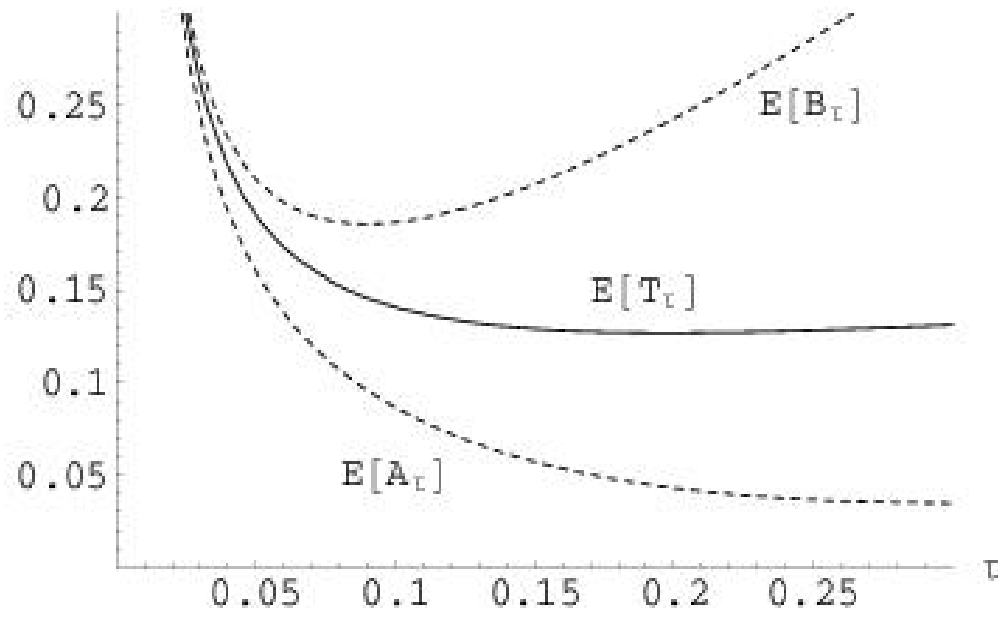
# geometric approximation for all moments

restart is bernoulli trial, approximate number of trials before completion

$$A_\tau = k(\tau + c) + 0 \quad \text{with prob. } (1 - F(\tau))^k F(\tau)$$

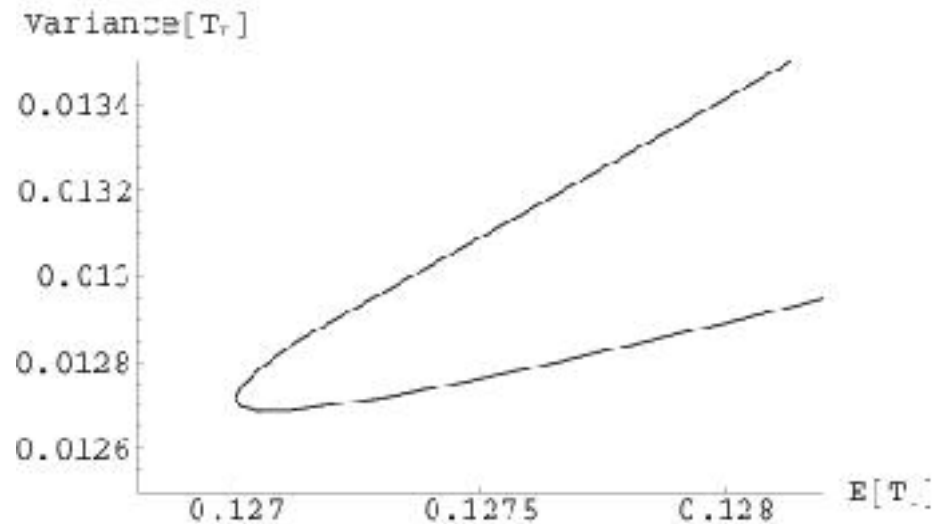
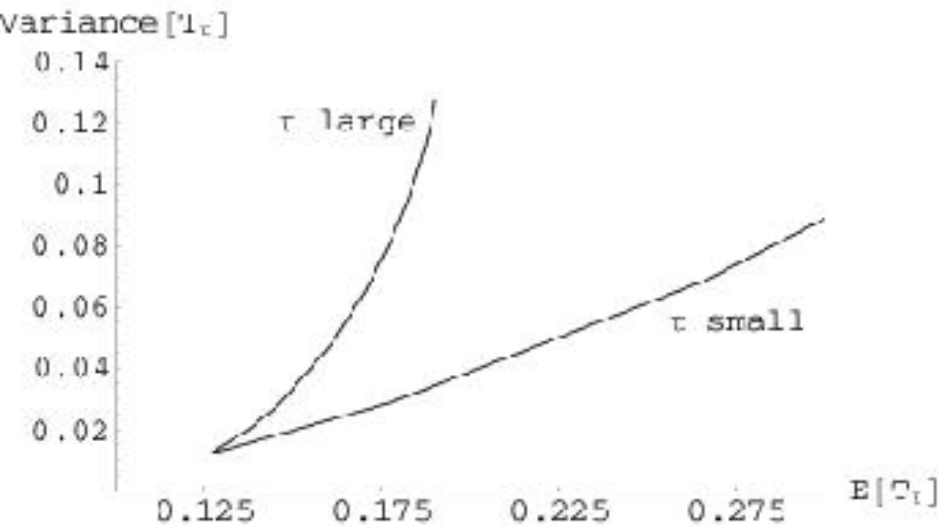
$$B_\tau = k(\tau + c) + \tau \quad \text{with prob. } (1 - F(\tau))^k F(\tau)$$

Approximation  $E[T_\tau]$



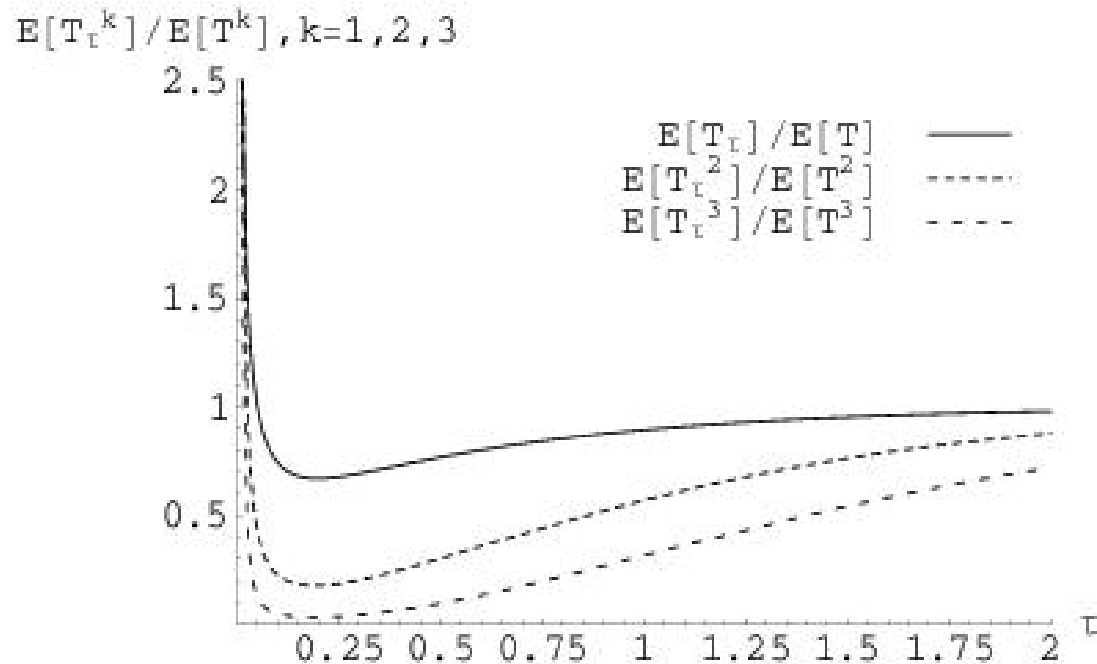
# cuspl point

## unbounded number of restarts



in general optimum for mean and variance is not the same

# length of restart interval



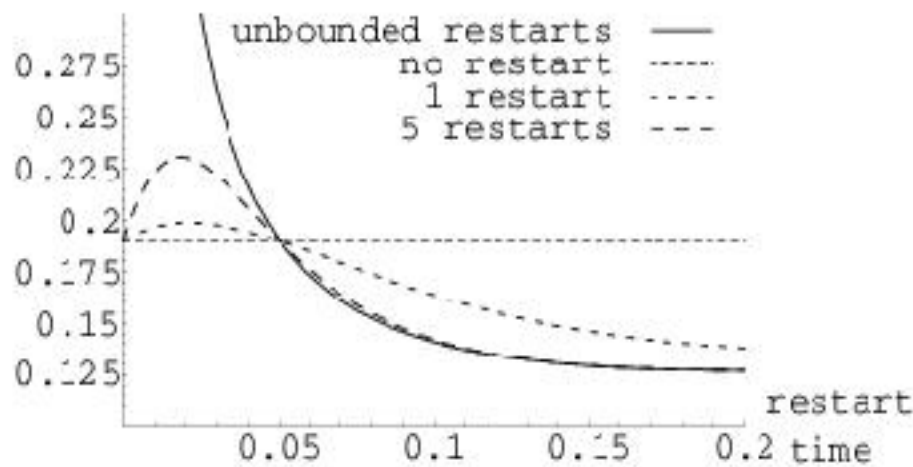
- a rough estimate should rather be a little bigger
- more gain for higher moments
- the more restarts the better:

$$E[T_\tau] < E[T] \Leftrightarrow E[T_\tau] < E[T_{\tau^{K+1}}] < E[T_{\tau^K}] < \dots < E[T], \quad K \geq 1$$

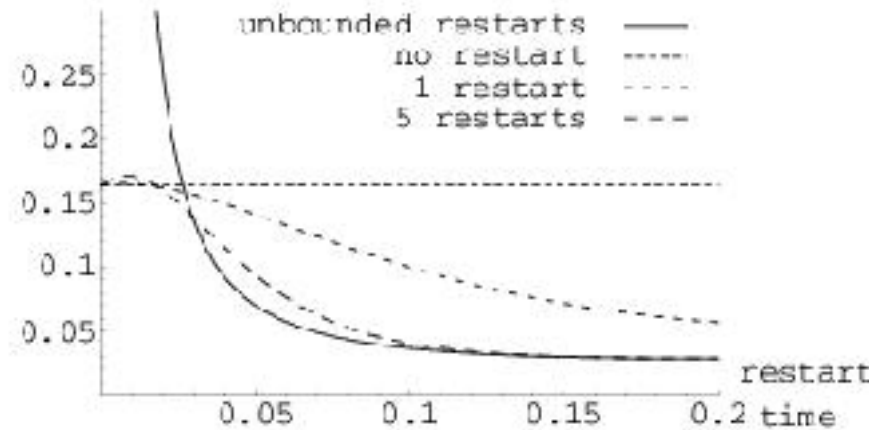
- infinite moments become finite under restart

# number of restarts

mean completion time



second moment completion time



For the first moment there is one point, in which the number of restarts makes no difference. For higher moments there is no such point.

# conclusion

	<b>first moment</b>	<b>higher moments</b>
<b>finite # restarts</b>	backward	forward/backward iteration
<b>infinite # restarts</b>	constant	first moment approximation & forward/backward

- higher moments benefit more than first moment
- infinite moments become finite under restart
- choose restart times not too small
- resolved problem of sensitivity to shifts with forward/backward